

Beyond Gbps Turbo Decoder on Multi-Core CPUs

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Software Implementations of FEC decoders

Growing interest for Software Defined Radio (SDR)

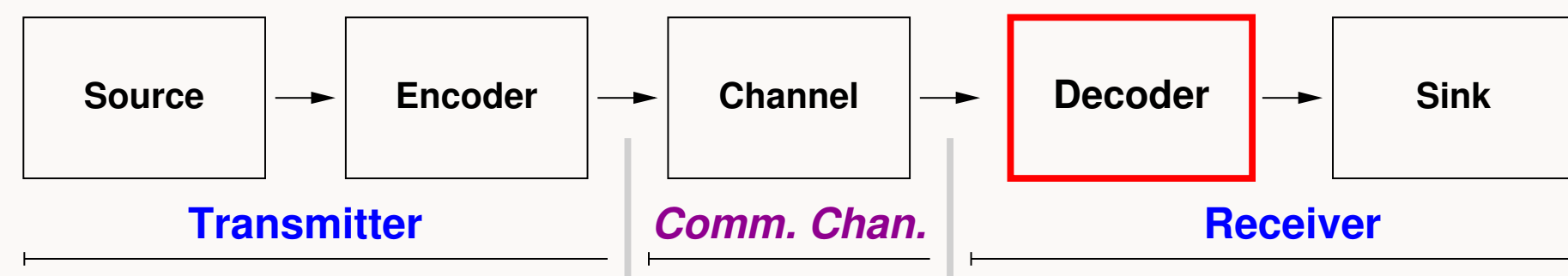


Figure 1: Simplified communication chain

Leverage powerful, energy efficient procs (x86, ARM):

- Validate and optimize new algorithms
- Implement real systems with real time performance
 - Enable Cloud computing-based architecture for Radio Access Networks (C-RAN)
 - Reduce dev. cost and time to market

→ Need for efficient software implementations to limit the energy consumption with high throughput.

Turbo-coding / decoding

A turbo code is a parallel concatenation of two component convolutional codes.

The turbo-decoding process is an iterative method in which two soft-input soft-output (SISO) decoders exchange extrinsic information via an interleaver.

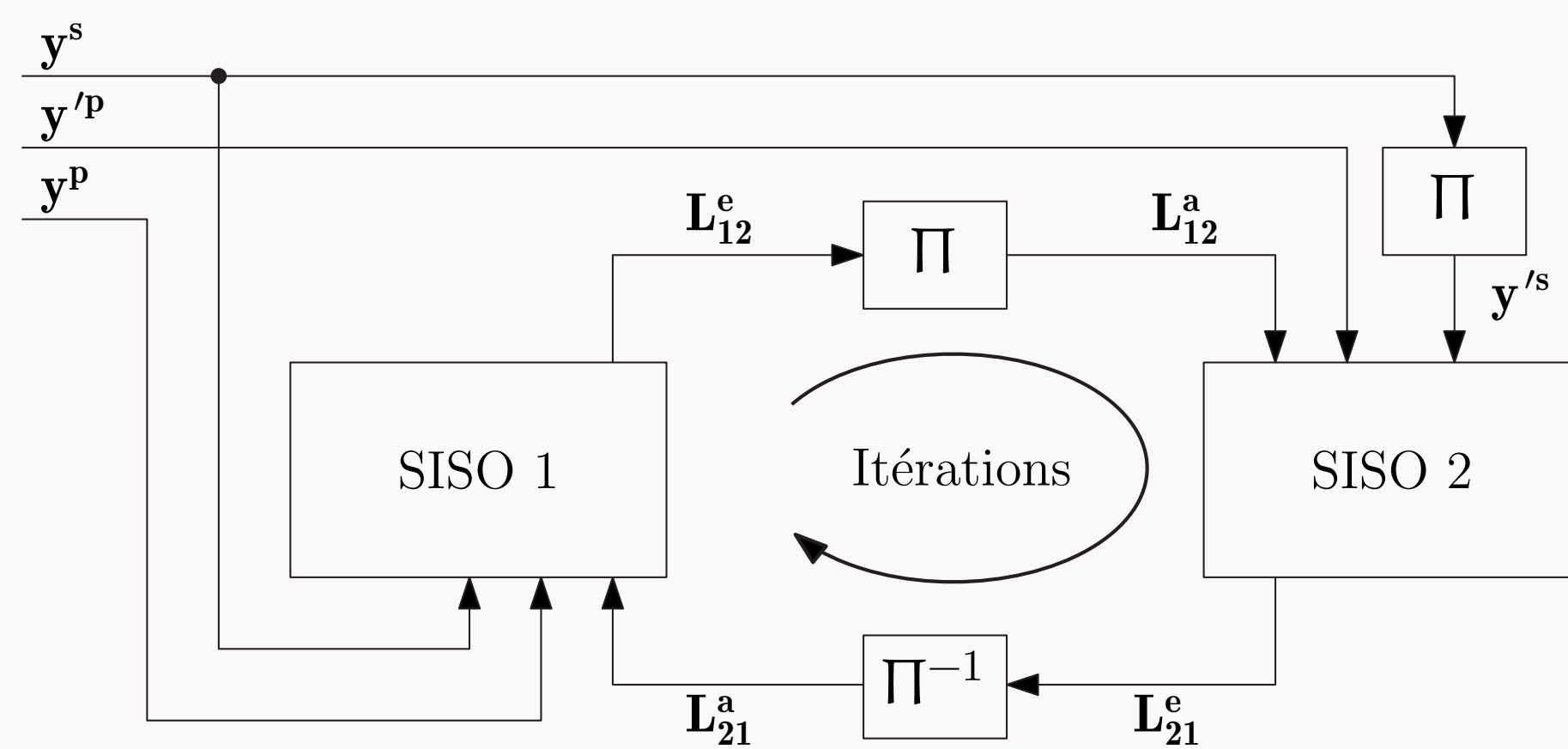


Figure 2: Turbo-decoding process

Loop merging in BCJR implementation

Standard BCJR implementation:

- for all frames do ▷ Sequential loop
- for $k = 0; k < K; k = k + 1$ do ▷ Parallel loop
- $\gamma^k \leftarrow \text{computeGamma}(L_{sys}^k, L_p^k, L_e^k)$
- $\alpha^0 \leftarrow \text{initAlpha}()$
- for $k = 1; k < K; k = k + 1$ do ▷ Sequential loop
- $\alpha^k \leftarrow \text{computeAlpha}(\alpha^{k-1}, \gamma^{k-1})$
- $\beta^{K-1} \leftarrow \text{initBeta}()$
- for $k = K - 2; k \geq 0; k = k - 1$ do ▷ Sequential loop
- $\beta^k \leftarrow \text{computeBeta}(\beta^{k+1}, \gamma^k)$
- for $k = 0; k < K; k = k + 1$ do ▷ Parallel loop
- $L_e^k \leftarrow \text{computeExtrinsic}(\alpha^k, \beta^k, \gamma^k)$

Loop merging BCJR implementation

- for all frames do ▷ Vectorized loop
- $\alpha^0 \leftarrow \text{initAlpha}()$
- for $k = 1; k < K; k = k + 1$ do ▷ Sequential loop
- $\gamma^{k-1} \leftarrow \text{computeGamma}(L_{sys}^{k-1}, L_p^{k-1}, L_e^{k-1})$
- $\alpha^k \leftarrow \text{computeAlpha}(\alpha^{k-1}, \gamma^{k-1})$
- $\gamma^{K-1} \leftarrow \text{computeGamma}(L_{sys}^{K-1}, L_p^{K-1}, L_e^{K-1})$
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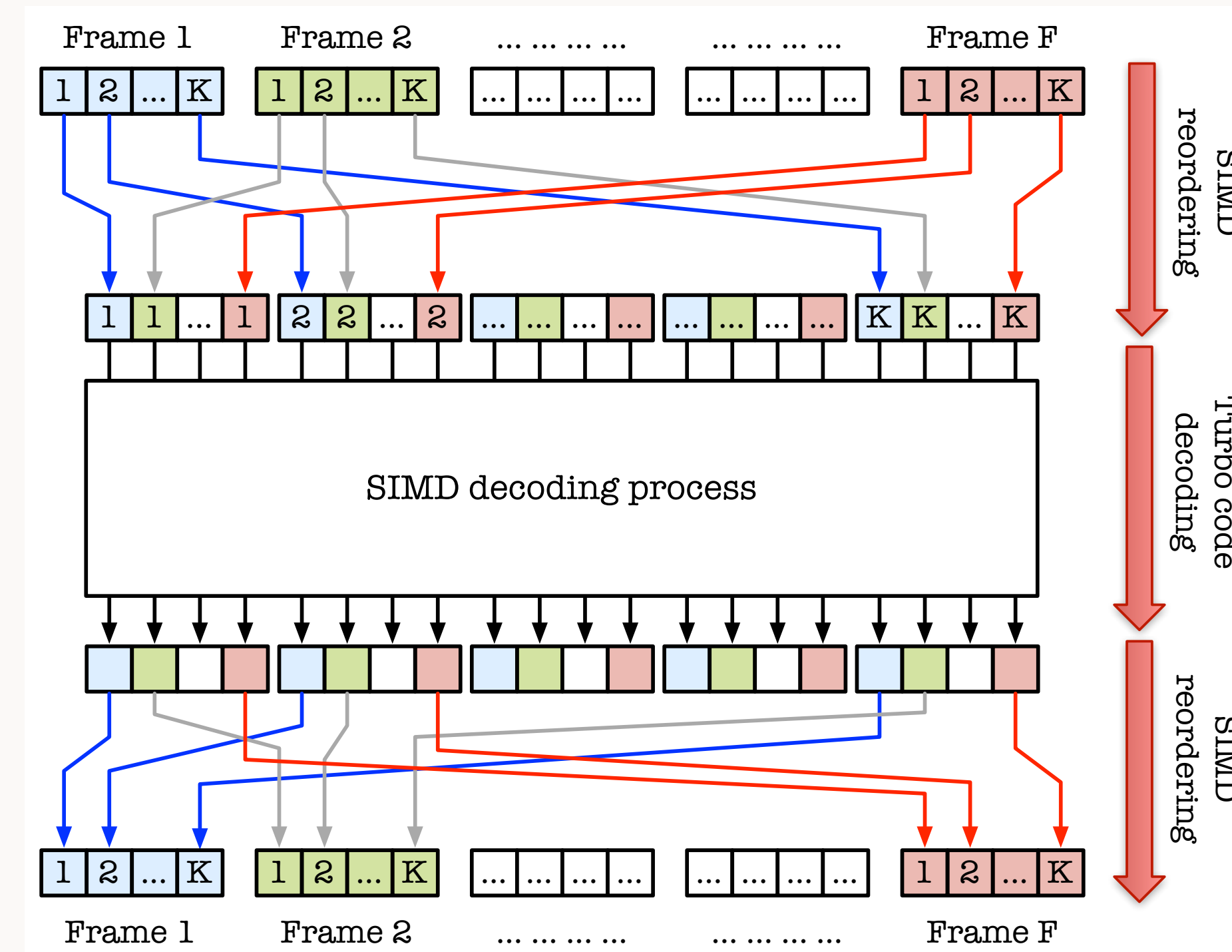
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Contribution of this Work

Two categories of parallelism in Turbo-decoding:

- Intra frame parallelism** : a single codeword is processed at the time. Computation within the turbo-decoding process are parallelized (trellis transitions, BCJR computations, sub-blocks, ...)
- Inter frame parallelism** : several frames are processed at the same time. This increases latency but allows more regular memory accesses.



Contribution :

In this work, we propose a **generic and flexible CPU implementation of a turbo decoder** that exclusively uses **inter-frame parallelism**. Experimental results show that our turbo decoder outperforms existing implementations in terms of throughput and energy efficiency.

The software platform: A Fast Forward Error Correction Tool (AFF3CT)

AFF3CT: a software dedicated to simulations of digital communications with channel coding

<http://aff3ct.github.io>

- Support different coding scheme: **Polar, Turbo, Convolutional, Repeat and Accumulate** and LDPC (coming soon)
- Very fast simulations, take advantage of today CPUs architecture (**hundreds of Mb/s on Intel Core i5/7**)
 - Written in C++11 (**SystemC/TLM support**)
 - Monte-Carlo **multi-threaded** simulations
 - Upto **1000 times faster than MATLAB** code
- Portable**: run on Linux, Mac OS X and Windows
- Open-source code** (under MIT license)
- For Turbo coding simulations, the following items are configurable: generator polynomial, interleaver, SISO

heuristic (log-MAP, max-log-MAP,...), puncturing, trellis termination.

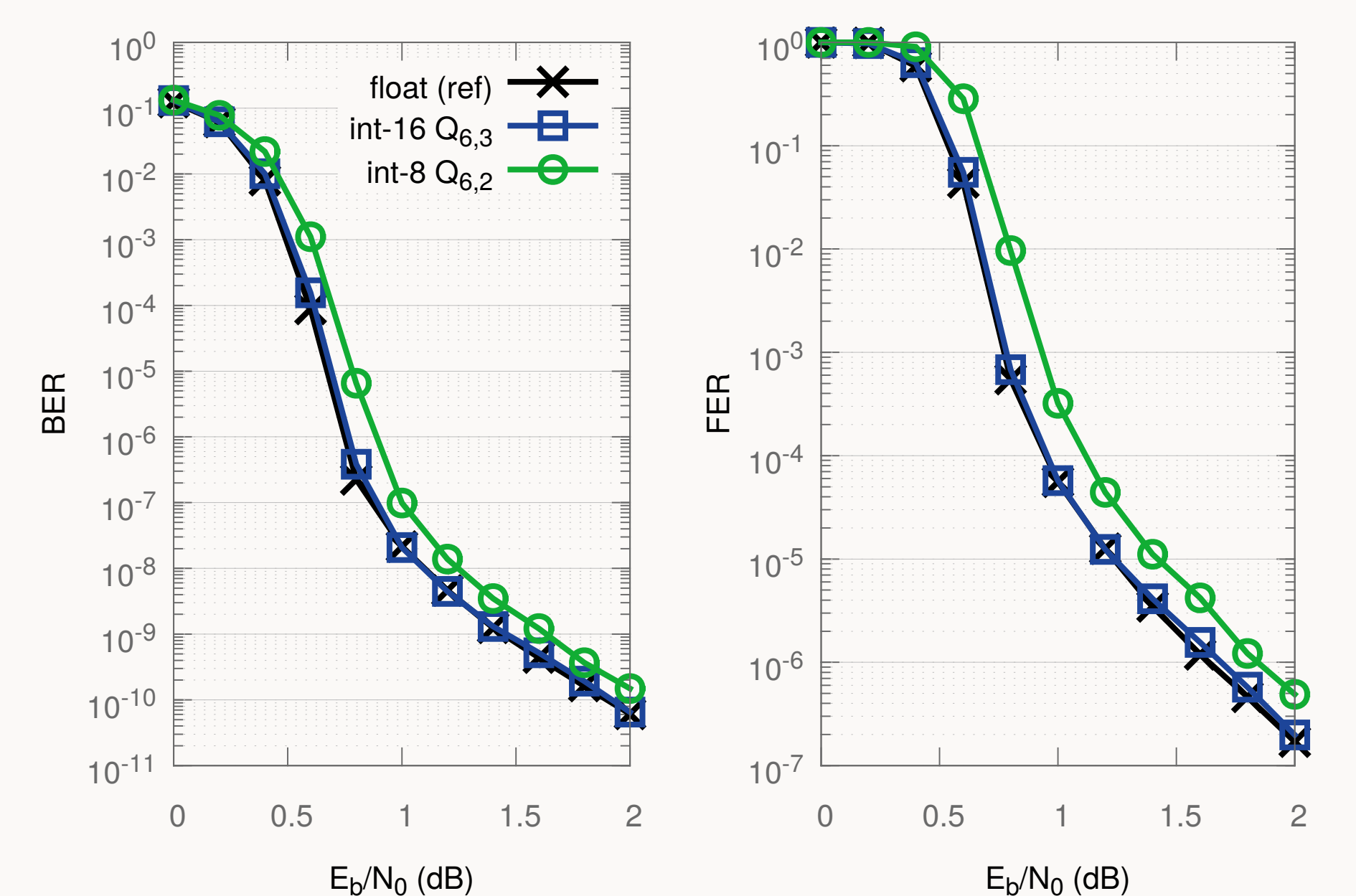


Figure 4: Simulated BER and FER of the $K = 6144, R = 1/3$ LTE Turbo code with AFF3CT

Experiments and Measurements

Work	Year	Platform	Arch.	Hardware and decoder parameters						Decoding performances				Metrics						
				TDP Watts	Cores or SM	Freq. GHz	Algorithm	Pre. bit	SIMD length	Inter level	K	Iters	BER at 0.7 dB	FER	Lat. μ s	Thr. Mbps	NThr. Mbps	TNDC	E_d nJ	
GPU-based	[1]	2010	Tesla C1060	Tesla	200	15	1.30	ML-MAP	32	16	100	6144	5	1e-04	—	76800	8.0	2.1	0.135	5000
	[2]	2011	GTX 470	Fermi	215	14	1.22	ML-MAP	32	32	100	6144	5	4e-05	—	20827	29.5	8.6	0.270	1458
	[3]	2012	Tesla C2050	Fermi	247	14	1.15	L-MAP	32	32	32	11918	5	—	—	108965	3.5	1.1	0.035	14114
	[4]	2012	9800 GX2	Tesla	197	16	1.50	ML-MAP	32	16	1	6144	5	1e-02	—	3072	2.0	0.4	0.025	19700
	[5]	2013	GTX 550 Ti	Fermi	116	6	1.80	EML-MAP	32	32	1	6144	6	1e-02	—	72*	85.3	47.4	1.482	227
	[6]	2013	GTX 580	Fermi	244	16	1.54	ML-MAP	32	32	1	6144	6	3e-04	—	1660	3.7	0.9	0.030	10090
	[7]	2013	GTX 480	Fermi	250	15	1.40	EML-MAP	32	32	1	6144	6	—	—	50*	122.8	35.1	1.098	339
	[8]	2013	GTX 680	Kepler	195	8	1.01	EML-MAP	32	192	16	6144	6	—	1e-02	2657	37.0	27.5	0.144	878
	[9]	2014	Tesla K20c	Kepler	225	13	0.71	ML-MAP	32	192	1	6144	5	1e-04	—	1097	5.6	3.0	0.015	8036
	[10]	2014	GTX 580	Fermi	244	16	1.54	BR-SOVA	8	32	4	6144	5	2e-02	—	192*	127.8	25.9	0.810	382
CPU-based	[11]	2011	i7-960	Nehalem	130	1	3.20	ML-MAP	16	8	1	1008	8	3e-03	7e-02	138	7.3	18.3	2.280	2226
	[12]	2012	X5670	Westmere	95	6	2.93	EML-MAP	8	16	6	5824	3	6e-02	—	157	222.6	38.0	2.373	142
	[8]	2013	i7-3770K	Ivy Bridge	77	4	3.50	EML-MAP	16	8	4	6144	6	—	1e-01	323	76.2	32.7	4.080	168
	this work	2016	E5-2650	Ivy Bridge	95	8	2.50	EML-MAP	16	8	16	6144	6	6e-06	6e-03	3665	107.3	32.2	4.014	148
			i7-4960HQ	Haswell	47	4	3.20									2212	88.9	41.7	5.208	88
			2x E5-2680v3	Haswell	240	24	2.50									2657	443.7	44.4	5.544	90
			E5-2650	Ivy Bridge	95	8	2.50									3492	225.2	67.6	4.224	70
			i7-4960HQ	Haswell	47	4	3.20									2837	138.6	65.0	4.062	57
2x E5-2680v3	Haswell	240	24	2.50	3293	716.4	71.6	4.476	56											

Conclusion

In this work a generic and flexible CPU implementation of a turbo decoder that exclusively uses inter-frame parallelism. Experimental results show that our turbo decoder outperforms existing implementations in terms of throughput and energy efficiency.

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